

More on the Automatic Search for Differential Trails in NORX (Work in Progress)

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1 Motivation

2 NORX

3 Automatic Search for Trails

4 Results

5 Conclusions

OUTLINE

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RESISTANCE OF NORX AGAINST DC

- Designers give bounds against DC [AJN14]
- Use SAT-solver; memory is exhausted for more rounds
- Bounds based on best trails for up to $F^{2.0}$ rounds

W	32				64			
Scenario	init _N	init _{N,K}	rate	full	init _N	init _{N,K}	rate	full
$F^{0.5}$	6	2	2	0	6	2	2	0
$F^{1.0}$	(60)	22	10	2	(53)	22	12	2
$F^{1.5}$	(60)	(40)	(31)	12	(53)	(35)	(27)	12
$F^{2.0}$	(61)	(45)	(34)	(27)	(51)	(37)	(30)	(23)

Scenario: modify the nonce (init_N), nonce + key (init_{N,K}), rate words (rate), full state (full).

MOTIVATION

Research Goal

Provide tighter bounds than the ones reported by [AJN14]

Disclaimer: Work-in-progress; preliminary results.

OUR CONTRIBUTIONS

- ➊ New algorithm for finding optimal trails – **Best Search (BS)**
- ➋ Heuristic version of BS – **Heuristic Search (HS)**
- ➌ New (sub-optimal) trails on up to $F^{2.0}$ rounds with HS

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OVERVIEW OF NORX

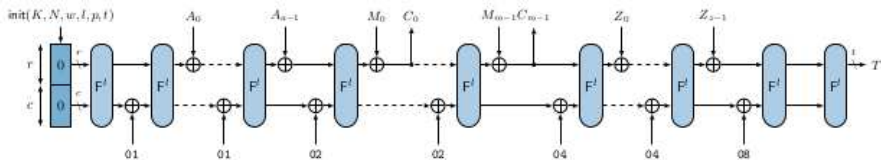
- Word size: $W \in \{32, 64\}$ bits
- Rounds: $1 \leq R \leq 63$
- Parallelism: $0 \leq D \leq 255$
- Tag size: $|A| \leq 10W$

NORXW-R-D	Nonce (2W)	Key (4W)	Tag (4W)	Classification
NORX64-4-1	128	256	256	Standard
NORX32-4-1	64	128	128	Standard
NORX64-6-1	128	256	256	High security
NORX32-6-1	64	128	128	High security
NORX64-4-4	128	256	256	High throughput

Credits: Philipp Jovanovic, ESORICS 2014.

NORX = NO(T A)RX

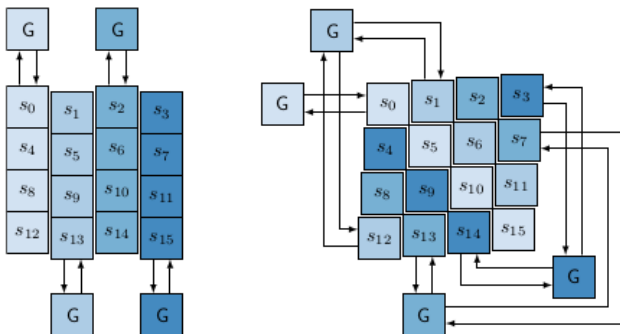
- Sponge structure based on the monkeyDuplex construction
- LRX permutation: $\oplus, \ggg, \wedge, \lll 1$
- Non-linear component: $H(x, y) = (x \oplus y) \oplus ((x \wedge y) \lll 1)$
- No S-box; No modular addition



Credits: NORX Specification <https://norx.io/>

PERMUTATION F

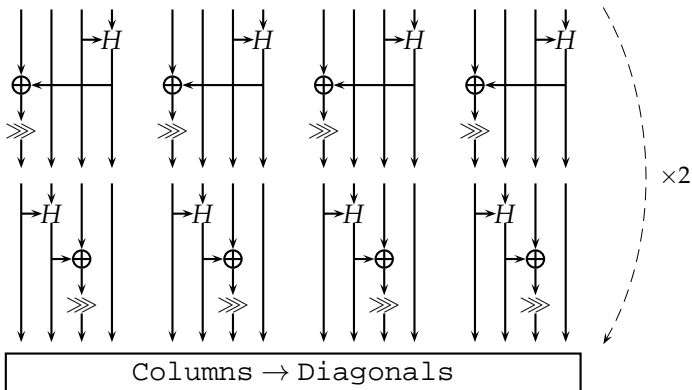
F is composed of **G -circuit** (next slide) applied in parallel first to each of the 4 columns of the state followed by an application to each of the 4 diagonals of the state: $F = F_{\text{dia}} \circ F_{\text{col}}$



Credits: NORX Specification <https://norx.io/>

HALF-ROUND: $F^{0.5} = F_{\text{col}}$

4 parallel app. of the G -circuit, where $H(x, y) = (x \oplus y) \oplus ((x \wedge y) \ll 1)$.

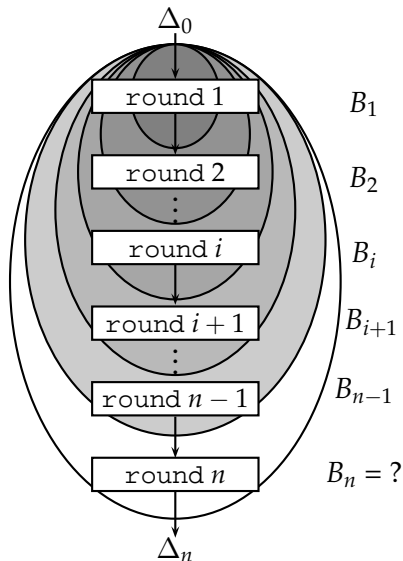


Note: Initialization = F^8 ; Data processing = F^4 .

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Matsui's Algorithm



Input: best p for $n - 1$ rounds:

$$B_1, B_2, \dots, B_{n-1}; \bar{B}_n$$

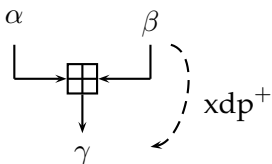
Output: best p for n rounds:

$$B_n$$

if $P_1 P_2 \dots P_i B_{n-i} \geq \bar{B}_n : i \leftarrow i + 1$

if $i = n: B_n \leftarrow \bar{B}_n$

MATSUI'S ALGORITHM FOR ARX [BVLC16]



$$2^{-\text{hw}(-\text{eq}(\alpha, \beta, \gamma) \wedge \text{mask}_{n-1})} \text{ [LM01]}$$

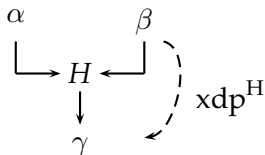
Proposition (Monotonicity of xdp^+)

xdp^+ is monotonously decreasing with the word size w of α, β, γ :

$$\tilde{p}_1 \geq \tilde{p}_2 \dots \geq \tilde{p}_{w-1} \geq \tilde{p}_w = \text{xdp}^+(\alpha, \beta \rightarrow \gamma) ,$$

where $\tilde{p}_i = \text{xdp}^+(\alpha[i-1:0], \beta[i-1:0] \rightarrow \gamma[i-1:0]) : w \geq i \geq 1$, is the probability of the partial differential composed of the i LS bits of α, β, γ .

MONOTONICITY OF xdp^H



$$H(x, y) = (x \oplus y) \oplus ((x \wedge y) \ll 1)$$

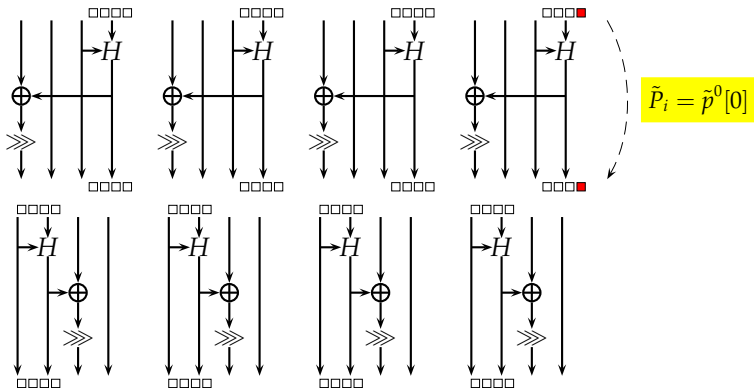
The Differential Probability of H [AJN14]

$$\text{xdp}^H(\alpha, \beta \rightarrow \gamma) = \begin{cases} 2^{-\text{hw}((\alpha \vee \beta) \ll 1)} & \iff (\alpha \oplus \beta \oplus \gamma) \wedge (\neg((\alpha \vee \beta) \ll 1)) = 0 \\ 0, & \text{otherwise} \end{cases}$$

Proposition (Monotonicity of xdp^H)

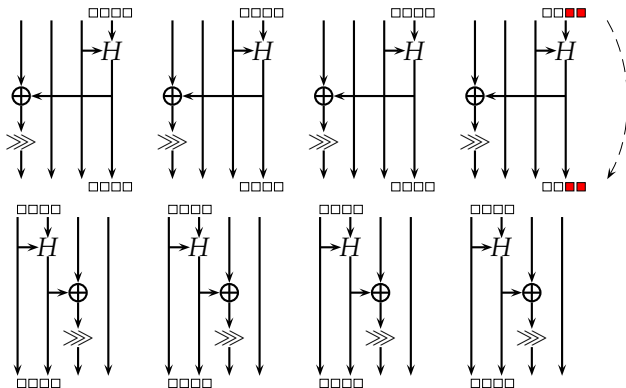
xdp^H is monotonously decreasing with the word size of α, β, γ .

BEST SEARCH (BS): ROUNDS i AND $i + 1$



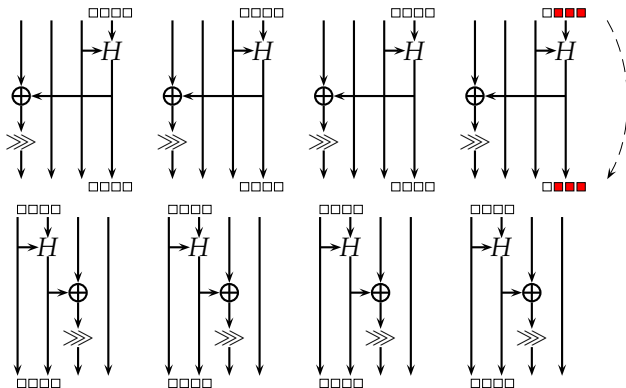
if $P_1 P_2 \dots \tilde{P}_i B_{n-i} \geq \bar{B}_n$ assign next bit

BEST SEARCH (BS): ROUNDS i AND $i + 1$



if $P_1 P_2 \dots \tilde{P}_i B_{n-i} \geq \bar{B}_n$ assign next bit

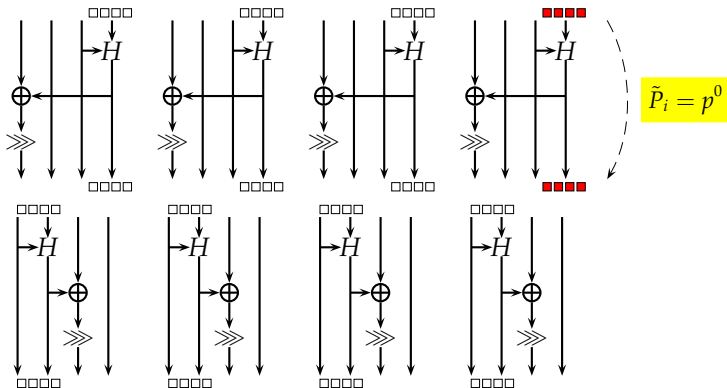
BEST SEARCH (BS): ROUNDS i AND $i + 1$



$$\tilde{P}_i = \tilde{p}^0[0:2]$$

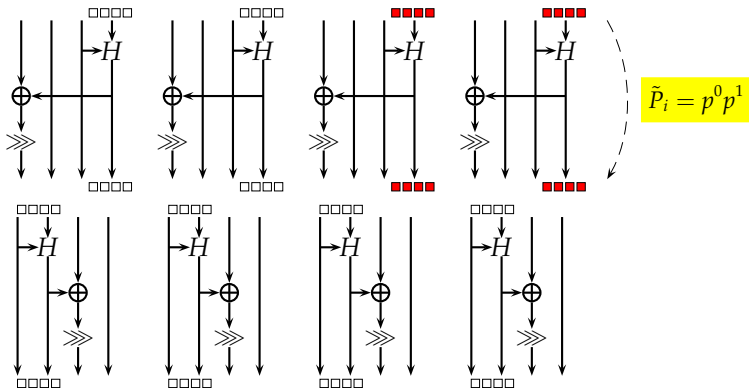
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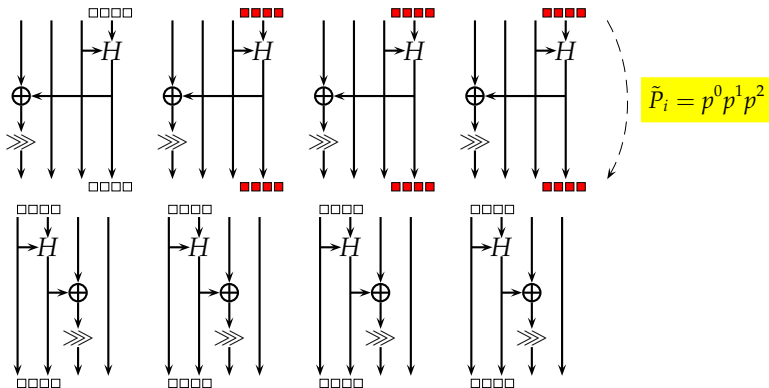
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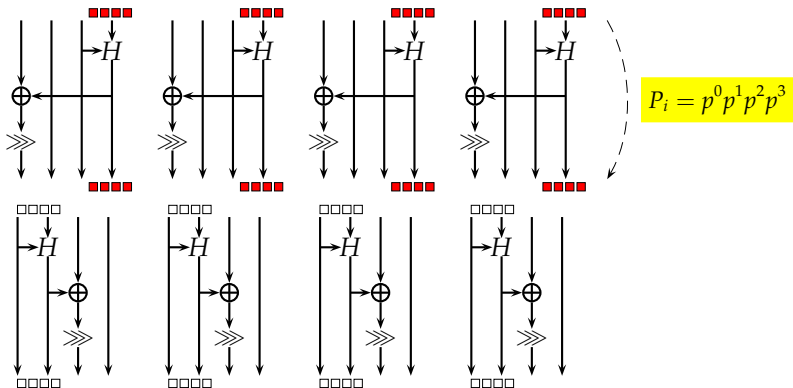
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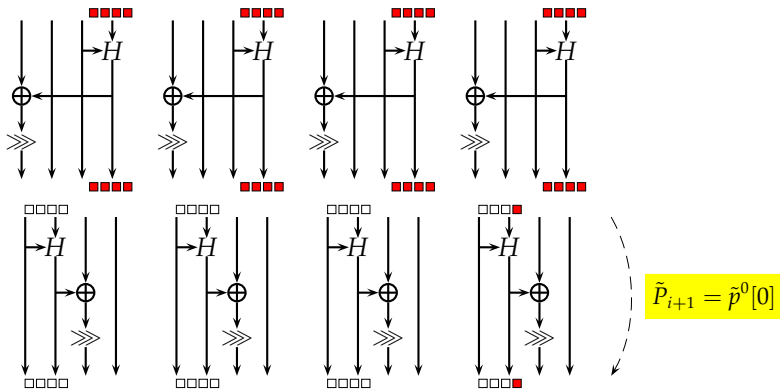
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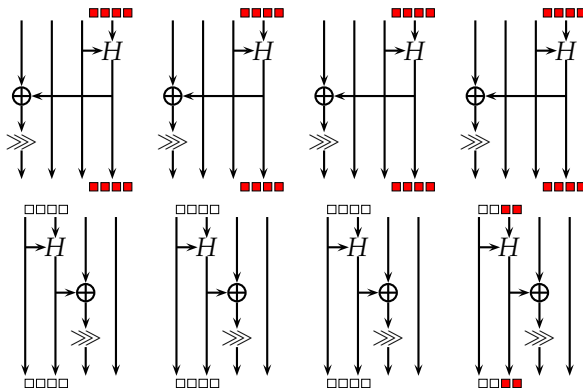
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BEST SEARCH (BS): ROUNDS i AND $i + 1$



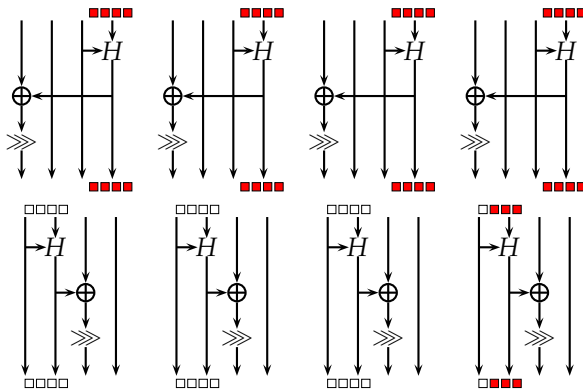
if $P_1 P_2 \dots P_i \tilde{P}_{i+1} B_{n-i-1} \geq \bar{B}_n$ assign next bit

BEST SEARCH (BS): ROUNDS i AND $i + 1$



if $P_1 P_2 \dots P_i \tilde{P}_{i+1} B_{n-i-1} \geq \bar{B}_n$ assign next bit

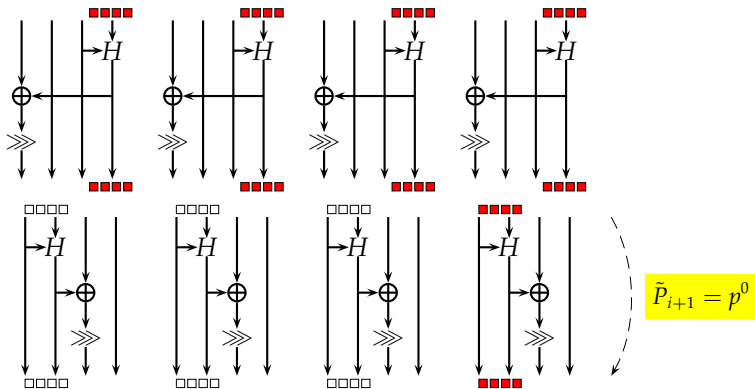
BEST SEARCH (BS): ROUNDS i AND $i + 1$



$$\tilde{P}_{i+1} = \tilde{p}^0[0 : 2]$$

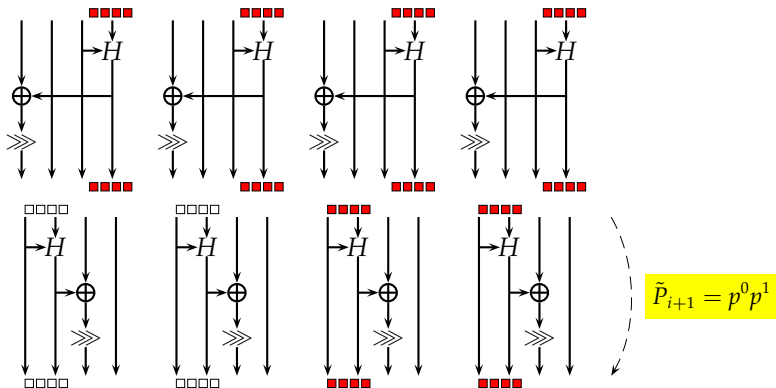
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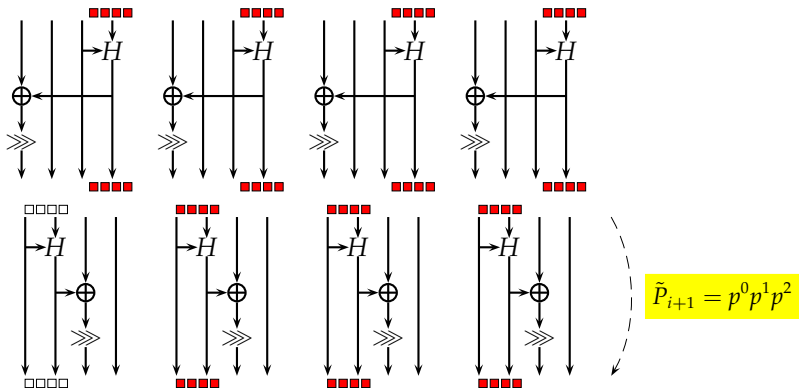
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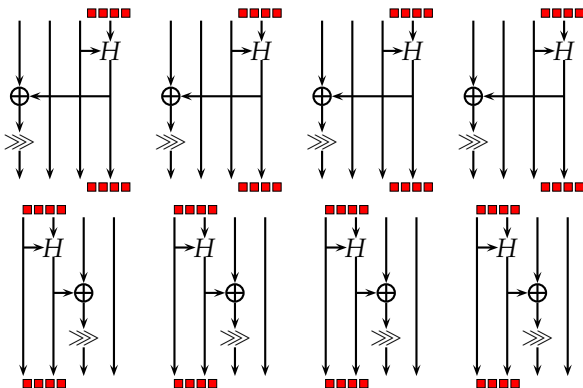
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BEST SEARCH (BS): ROUNDS i AND $i + 1$



$$P_{i+1} = p^0 p^1 p^2 p^3$$

if $P_1 P_2 \dots P_i P_{i+1} B_{n-i-1} \geq \bar{B}_n$ assign next bit

COMPLEXITY OF BS

Time and Memory Requirements

- Negligible memory (**good**)
- Time is proportional to num. of rounds and word size (**bad**)
- Feasible up to $F^{0.5}/F^{1.0}$ rounds (SAT-solver covers up to $F^{1.0}/F^{1.5}$)

Time Measurements for NORX32 and NORX64

- **BS** $F^{0.5}/F^{1.0} \approx 49$ days; negl. RAM (3.4GHz PC)
- **SAT** $F^{1.0}/F^{1.5} \approx 8$ hours; 49 GB RAM [AJN14]

HEURISTIC SEARCH (HS)

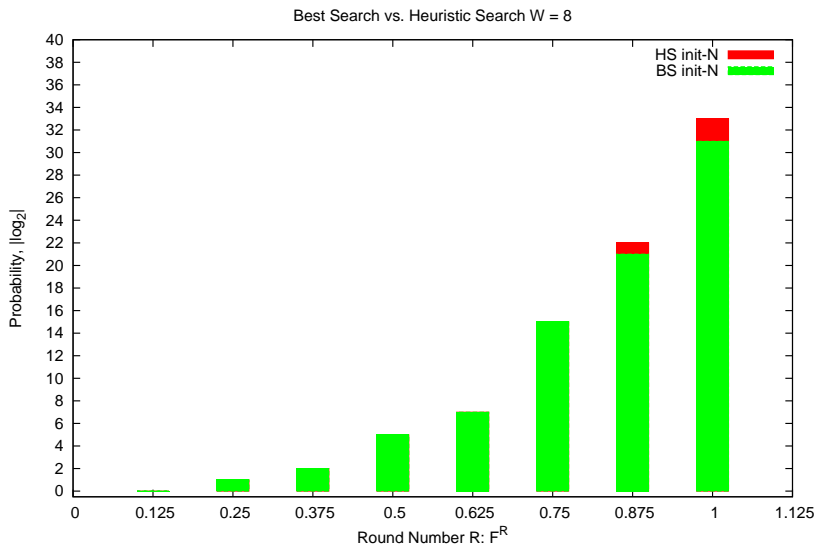
Heuristics to lower the time complexity of BS

- 1 Time Limit (TL)
 - How long to wait before the recursive call is terminated
- 2 Maximum Number of Tries (MT)
 - Number of times that we restart the search after the TL is exceeded.
- 3 Branch Factor Percentage x (BF)
 - In x out of 100 cases branch and explore both 0 and 1 for a given bit. In the remaining cases set the bit to 0.
 - Intuition: due to $\text{xdp}^H(\alpha, \beta \rightarrow \gamma) = 2^{-\text{hw}((\alpha \vee \beta) \ll 1)}$

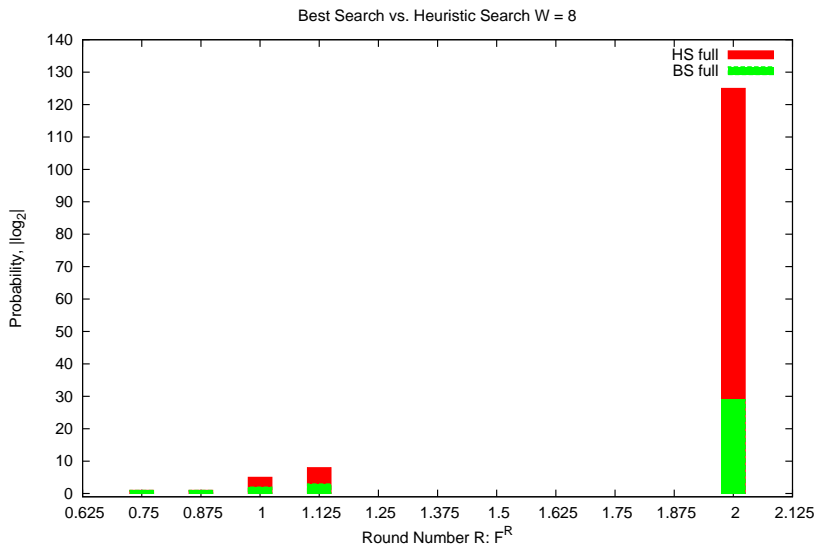
TL, sec	1	1	1	30	60	60	600	3600
MT	65535	1024	512	256	256	256	64	1
BF	30	50	75	50	50	50	75	100

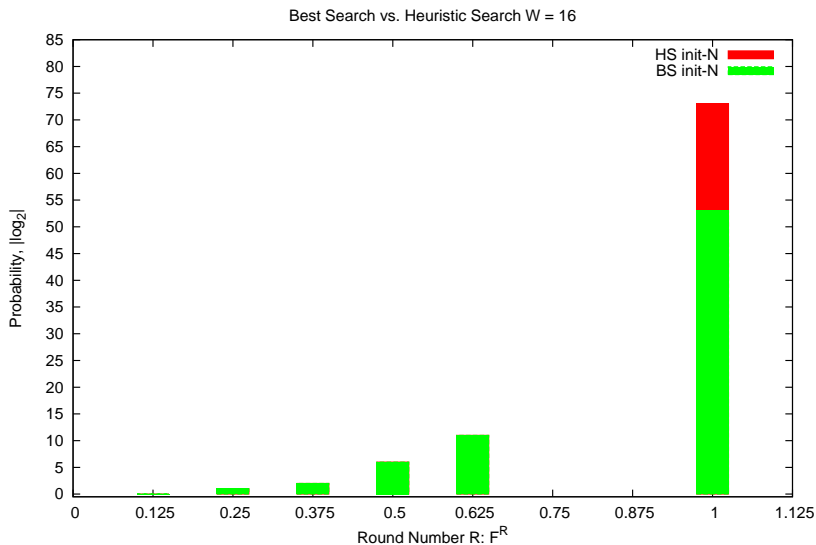
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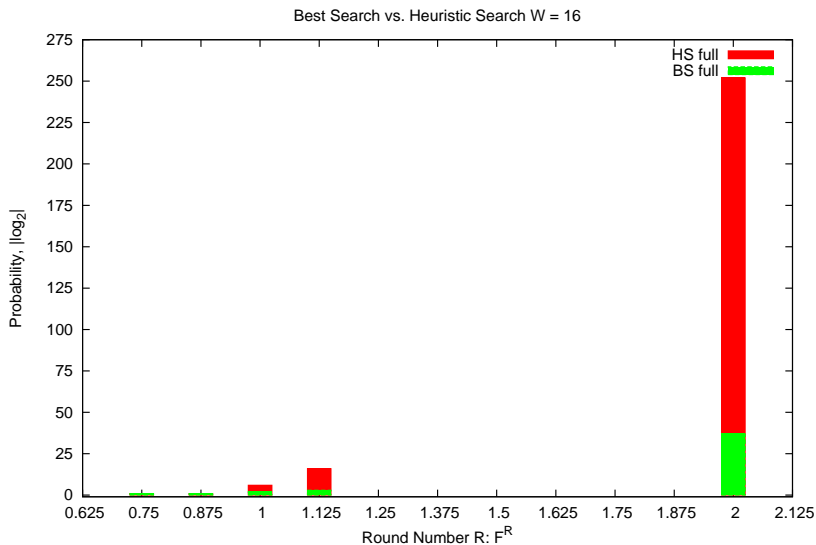
NORX8: BS vs. HS, SCENARIO: INIT_N

NORX8: BS vs. HS, SCENARIO: FULL



NORX16: BS vs. HS, SCENARIO: INIT_N

NORX16: BS vs. HS, SCENARIO: FULL



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CONCLUSIONS AND FUTURE WORK

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$F^{0.5}$	6	2	2	0	6	2	2	0
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- New heuristic algorithm for diff. search in NORX
- Matsui-like; Negligible memory; Manageable time
- Accuracy drastically degrades in the num. rounds and word size

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- New trails on up to $F^{2.0}$ rounds \implies new diff. bounds
- Designers' bounds are too pessimistic (designer's PoV)
- Our bounds are too optimistic (designer's PoV)
- Need better heuristics; new (algorithmic) optimizations; BS + SAT

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Main Message

NORX is a conservative design with large security margin against DC

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Thank you for your attention!

Questions?

REFERENCES I



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Analysis of NORX: Investigating differential and rotational properties.

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